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balance while
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Tifting and other
physically
demanding tasks.
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It lays fundamental
groundwork in
legged locomotion,
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experiments.
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The team engineered the robot as simply a torso and two legs, and designed the system specifically to test lower-body tasks, such as locomotion and balance. As with its full-body counterpart, Little

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Locomotion over
different terrain
types, whether flat
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important for a wide

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Abstract—The
ability of legged
systems to traverse

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Highly-constrained environments depends by and large on the performance of their motion and balance controllers. This paper

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Two-legged robot mimics human balance while running and jumping. 6.

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